

Switchin regression and MSM models

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2019

Switching regression - model

Cross-section sample

- Regression equation

$$y_i = \mathbf{x}_{0i}\boldsymbol{\beta}_0 + u_{0i} \quad \text{for } s_i = 0 \quad (\text{State 0})$$

$$y_i = \mathbf{x}_{1i}\boldsymbol{\beta}_1 + u_{1i} \quad \text{for } s_i = 1 \quad (\text{State 1})$$

- Selection equation - model for binary variable

$$s_i = 0 \quad \text{for } \mathbf{z}_i\boldsymbol{\gamma} < u_i$$

$$s_i = 1 \quad \text{for } \mathbf{z}_i\boldsymbol{\gamma} \geq u_i$$

- Identification: among explanatory variables in selection equation we should include variables, which are not included in regression equation

Switching regression - random error assumptions

- We assume that random errors are *IID* - no autocorrelation (independence) and distributions are the same for all u_i
- Variance matrix of error terms

$$\Sigma = \begin{bmatrix} \sigma_{00} & \sigma_{02} & \sigma_{0u} \\ & \sigma_{11} & \sigma_{1u} \\ & & 1 \end{bmatrix}$$

- Usually we assume as well normality of error term

Switching regression - estimation

OLS estimation

- We assume normality of error term
- Fundamental problem, correlation between u_{i0} , u_{i1} and u_i

$$E(u_{i0} | \mathbf{z}_i \gamma \geq u_i) = -\sigma_{0u} \frac{\phi(\mathbf{z}_i \gamma)}{\Phi(\mathbf{z}_i \gamma)}$$

$$E(u_{i1} | \mathbf{z}_i \gamma < u_i) = \sigma_{1u} \frac{\phi(\mathbf{z}_i \gamma)}{\Phi(\mathbf{z}_i \gamma)}$$

- Conclusion: if \mathbf{z}_i includes some of the variables included in \mathbf{x}_{1i} or \mathbf{x}_{2i} then the condition, $E(u_{1i} | \mathbf{x}_{1i}) = 0$ and $E(u_{2i} | \mathbf{x}_{2i}) = 0$ is invalid.

Switching regression - estimation

ML estimator

- Likelihood function:

$$\begin{aligned} L(\beta_0, \beta_1, \sigma_{00}, \sigma_{11}, \sigma_{01}, \sigma_{0u}, \sigma_{1u}) \\ &= \prod_{i=1}^N \left[\int_{-\infty}^{z_i \beta} f(y_i - \mathbf{x}_{1i} \beta_1 | u_i) du_i \right]^{s_i} \\ &\times \left[\int_{z_i \beta}^{\infty} f(y_i - \mathbf{x}_{2i} \beta_1 | u_i) du_i \right]^{s_i - 1} \end{aligned}$$

Switching regression - special cases

- Sometimes *ML* estimation is difficult
- It is possible to use two-step estimator similar to the one used in Heckman model

Markov chain definition

- Values of random variable X_n are in finite set $\{s_1, s_2, \dots, s_r\}$
- Finite Markov chain

$$\Pr(X_n = j | X_0 = i_0, X_1 = i_1, \dots, X_{n-1} = i_{n-1}) = P(X_n = j | X_{n-1} = i)$$

- This process has a short memory, transition probability only depends on the state of the process in previous period
- Finite homogenous Markov chain has a following property:

$$P(X_n = j | X_{n-1} = i) = P(X_{n+s} = j | X_{n+s-1} = i) = p_{ij}$$

- For homogenous Markov chain, transition probabilities do not change over time

- Matrix of transition probabilities has a following form:

$$\mathbf{P} = \begin{bmatrix} p_{11} & p_{12} & \cdots & p_{1r} \\ p_{21} & p_{22} & \cdots & p_{2r} \\ \vdots & \vdots & & \vdots \\ p_{r1} & p_{r2} & \cdots & p_{rr} \end{bmatrix}$$

- p_{ij} has to satisfy following properties:

$$\sum_{j=1}^r p_{ij} = 1$$
$$p_{ij} \geq 0$$

Markov switching model (MSM)

- Regression equation

$$y_t = \mathbf{x}_t \boldsymbol{\beta}_0 + \sigma_0 \varepsilon_t \quad \text{for } s_t = 0 \quad (\text{State 0})$$

$$y_t = \mathbf{x}_t \boldsymbol{\beta}_1 + \sigma_1 \varepsilon_t \quad \text{for } s_t = 1 \quad (\text{State 1})$$

- Selection equation - Markov chain with changing transition probabilities (nonhomogenous)

$$P(s_t = i | s_{t-1} = j, \mathbf{z}_t) = p_{ij}(\mathbf{z}_t)$$

- We assume that

$$s_t = 0 \quad \text{for} \quad \mathbf{z}_t \boldsymbol{\gamma}_{s_{t-1}} < u_t$$

$$s_t = 1 \quad \text{for} \quad \mathbf{z}_t \boldsymbol{\gamma}_{s_{t-1}} \geq u_t$$

so that

$$p_{s_{t-1},0}(\mathbf{z}_t) = 1 - \Phi(\mathbf{z}_t \boldsymbol{\gamma}_{s_{t-1}})$$

$$p_{s_{t-1},1}(\mathbf{z}_t) = \Phi(\mathbf{z}_t \boldsymbol{\gamma}_{s_{t-1}})$$

Transition matrix

$$P(\mathbf{z}_t) = \begin{bmatrix} 1 - \Phi(\mathbf{z}_t \boldsymbol{\gamma}_0) & \Phi(\mathbf{z}_t \boldsymbol{\gamma}_0) \\ 1 - \Phi(\mathbf{z}_t \boldsymbol{\gamma}_1) & \Phi(\mathbf{z}_t \boldsymbol{\gamma}_1) \end{bmatrix}$$

- We assume that unconditional Markov chain is stationary:

$$P(s_t = i | \bar{z}) = P(s = i | \bar{z}) \text{ for every } t$$

$$\begin{bmatrix} \varepsilon_t \\ u_t \end{bmatrix} \sim N\left(0, \begin{bmatrix} 1 & \rho \\ \rho & 1 \end{bmatrix}\right)$$

- We assume as well that the state in time t is unobservable

- Estimation usually done with *ML*
- In general case likelihood function complicated
- Special cases
 - exogenous switching: $\rho = 0$
 - pure Markov chain $\gamma_0 = \gamma_1 = \mathbf{0}$

- Joint density function for the sample

$$L(\theta) = \prod_{t=1}^T f(y_t | \Omega_t, \xi_{t-1}; \theta)$$

where $\xi_t = (y_t, y_{t-1}, \dots, y_1)$,

$\Omega_t = (\mathbf{x}_t, \mathbf{x}_{t-1}, \dots, \mathbf{x}_1, \mathbf{z}_t, \mathbf{z}_{t-1}, \dots, \mathbf{z}_1)$,

$\theta = (\beta_0, \sigma_0, \gamma_0, \beta_1, \sigma_1, \gamma_1, \rho)$.

- Density function for one observation

$$\begin{aligned} & f(y_t | \Omega_t, \xi_{t-1}; \theta) \\ &= \sum_i \sum_j f(y_t | s_t = i, s_{t-1} = j, \Omega_t, \xi_{t-1}; \theta) \times \\ & \Pr(s_t = i, s_{t-1} = j | \Omega_t, \xi_{t-1}; \theta) \end{aligned}$$

- Transition probability for a given observation we calculate recursively from Bayes theorem and using that

$$P(s_0 = i | \bar{z}) = P(s = i | \bar{z})$$

- so that:

$$\Pr(s_t = i, s_{t-1} = j | \Omega_t, \zeta_{t-1}; \theta) = p_{ij}(z_t) \Pr(s_{t-1} = j | \Omega_t, \zeta_{t-1}; \theta)$$

- Unconditional transition probabilities we calculate from Bayes theorem as follows:

$$\begin{aligned} & \Pr (s_t = i | \Omega_{t+1}, \zeta_t; \theta) \\ &= \Pr (s_t = i | \Omega_t, \zeta_t; \theta) \\ &= \frac{f (y_t, s_t = i | \Omega_t, \zeta_{t-1}; \theta)}{f (y_t | \Omega_t, \zeta_{t-1}; \theta)} \\ &= \frac{1}{f (y_t | \Omega_t, \zeta_{t-1}; \theta)} \times \\ & \sum_j f (y_t, s_t = i | s_{t-1} = j, \Omega_t, \zeta_{t-1}; \theta) \times \\ & \Pr (s_t = i, s_{t-1} = j | \Omega_t, \zeta_{t-1}; \theta) \end{aligned}$$

- in case, when $\rho = 0$

$$f(y_t | s_t = i, s_{t-1} = j, \mathbf{\Omega}_t, \boldsymbol{\zeta}_{t-1}; \boldsymbol{\theta}) = \frac{1}{\sigma_{s_{t-1}}} \phi\left(\frac{y_t - \mathbf{x}_t \boldsymbol{\beta}_{s_{t-1}}}{\sigma_{s_{t-1}}}\right)$$

- In general case the formula is more complex